

# Solving Systems of Polynomial Equations with Symmetries Using SAGBI-Gröbner Bases

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# Problem

Solving by **exact method** the polynomial system:

$$\left\{ \begin{array}{l} f_1(x_1, \dots, x_n) = 0 \\ \vdots \\ f_m(x_1, \dots, x_n) = 0 \end{array} \right. \quad \text{with } f_j \in R = \mathbb{K}[x_1, \dots, x_n]$$

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NP-hard even when  $\mathbb{K} = \mathbb{K}_2$

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- Sparse/Structured systems
- Systems s.t. **the set of solutions** is left invariant by the action of a **finite group**.

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☞ Try to identify families of systems which are easier to solve:

**In this talk:** sub problem of the previous case

- $f_i$  is invariant by the action of a **finite subgroup**  $G$  of  $\mathfrak{S}_n$ .

# Cyclic $n$

Well known benchmark is the cyclic  $n$  problem.

 G. Björk.

Functions of modulus 1 on  $\mathbf{Z}_n$ , whose Fourier transforms have constant modulus, and “cyclic  $n$ -roots”.

In J.S. Byrnes and J.F. Byrnes, editor, *Recent Advances in Fourier Analysis and its Applications*, volume 315 of *Ser. C: Math. Phys. Sci.*, Kluwer, pages 131–140. NATO Adv. Sci. Inst., 1989.

## Example (Cyclic 5)

Consider the cyclic 5 problem:

$$\left\{ \begin{array}{l} f_1 = x_1 + x_2 + x_3 + x_4 + x_5 \\ f_2 = x_1x_2 + x_2x_3 + x_3x_4 + x_4x_5 + x_5x_1 \\ f_3 = x_1x_2x_3 + x_2x_3x_4 + x_3x_4x_5 + x_4x_5x_1 + x_5x_1x_2 \\ f_4 = x_1x_2x_3x_4 + x_2x_3x_4x_5 + x_3x_4x_5x_1 + x_4x_5x_1x_2 + x_5x_1x_2x_3 \\ f_5 = x_1x_2x_3x_4x_5 - 1 \end{array} \right.$$

# Gröbner bases destroy the symmetries

Computations: Gröbner basis, Triangular sets, ...



Destroy the symmetries of the system instead of using them !

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## Example (Cyclic 5)

A lexicographic Gröbner basis of the ideal generated by the cyclic 5 problem contains the univariate polynomial:


$$h(x_1) = x_1^{15} + 122x_1^{10} - 122x_1^5 - 1$$

which is *not invariant* by the cyclic group.



# Related Works

Computing the Gröbner basis in invariants rings:

 Using the primary and secondary invariants to reformulate the problem.



**B.Sturmfels.**

*Algorithms in Invariant Theory.*

Springer-Verlag, Wien, New York, 1993.




**A.Colin.**

Solving a system of algebraic equations with symmetries.

*Pure and applied algebra*, 117-118:195–215, 1997.

## Related Works

Computing the Gröbner basis in invariants rings:

 Using the primary and secondary invariants to reformulate the problem.

 [B.Sturmfels.](#)

 [A.Colin.](#)


 Difficult to compute the **generating set** of invariants rings !

### Example (Cyclic $n$ )

Group	cardinality of the generating set	CPU
cyclic 7	48	1.3 s
cyclic 8	65	1478 s

Cardinality and CPU time of generating sets of the invariant rings  
(Magma 2-14)

## Related Works

 Using the primary and secondary invariants to reformulate the problem.



The resulting system is very often **much difficult** to solve than the original system !

### Example (Cyclic $n$ )

Resulting system cyclic 5 problem: **17** equations and **17** variables.

### Experimental Fact:

Untractable when  $n > 6$ .

# Reynolds operator

$R = \mathbb{K}[x_1, \dots, x_n]$  and  $R^G$  is the ring of invariant polynomials.

## Definition

Let  $G$  be a finite group. The Reynolds operator of  $G$  is the map  $\mathfrak{R} : R \rightarrow R^G$  defined by the formula

$$\overline{\mathfrak{R}}(f) = \sum_{A \in G} f(A.X) \quad \text{and} \quad \mathfrak{R}(f) = \frac{\overline{\mathfrak{R}}(f)}{|G|}.$$

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## Proposition

Let  $\mathfrak{R}$  be the Reynolds operator of the finite matrix group  $G$ .

- (a)  $\mathfrak{R}$  is  $\mathbb{K}$ -linear in  $f$  :  $\mathfrak{R}(cf + g) = c\mathfrak{R}(f) + \mathfrak{R}(g)$
- (b) If  $f \in R$ , then  $\mathfrak{R}(f) \in R^G$ .
- (c) If  $f \in R^G$ , then  $\mathfrak{R}(f) = f$ .

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## Lemma

We fix  $<$  a monomial ordering.

Every  $f \in R^G$  can be written uniquely as  $f = \sum_{\alpha} c_{\alpha} \mathfrak{R}(t_{\alpha})$ , where  $c_{\alpha} \in \mathbb{K}$  and  $t_{\alpha} \in LT_{<}(R^G)$ .

# Reynolds operator

## Example (Cyclic $n$ )

Let  $G$  be the cyclic group generated by  $\{(1, 2, 3, 4, 5)\}$ . Consider  $f = x_1 x_2 x_3 + x_2 x_3 x_4 + x_3 x_4 x_5 + x_4 x_5 x_1 + x_5 x_1 x_2 + 3x_1 + 3x_2 + 3x_3 + 3x_4 + 3x_5$  wrt lex order  $x_1 > x_2 > x_3 > x_4 > x_5$ .

$$f = \mathfrak{R}(f) = \overline{\mathfrak{R}}(x_1 x_2 x_3) + 3 \overline{\mathfrak{R}}(x_1)$$

Very compact representation !